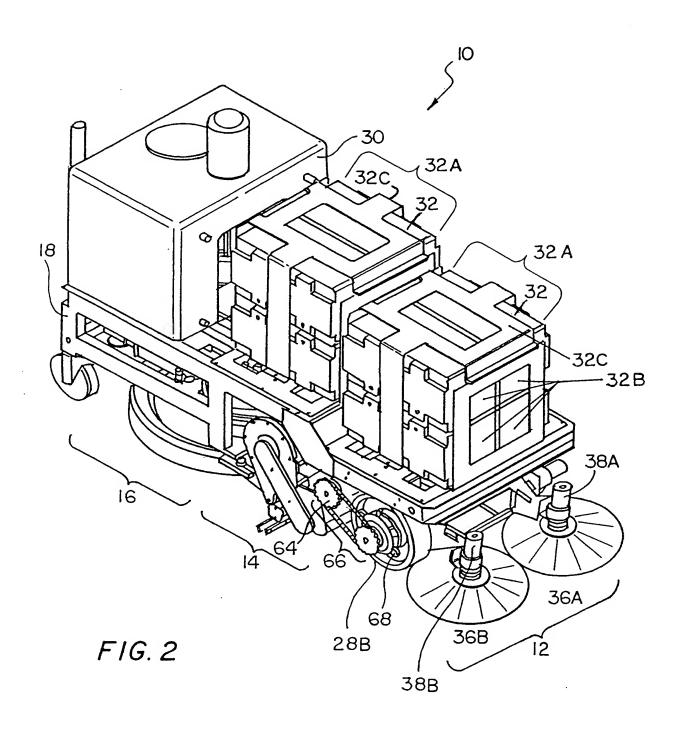
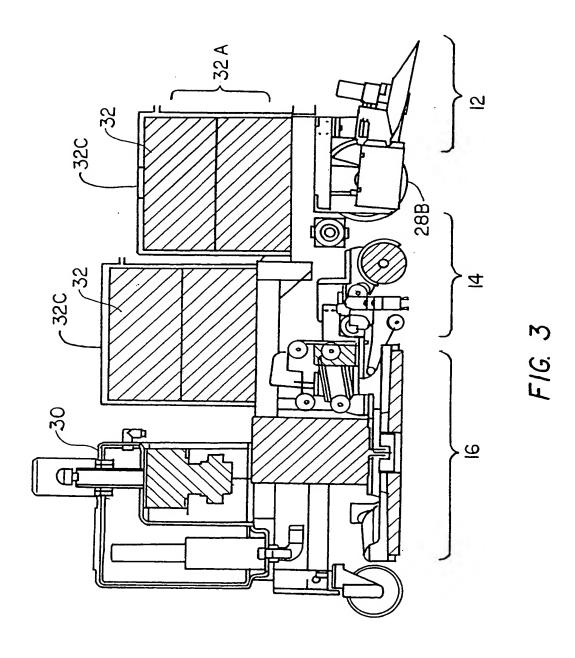


F16.

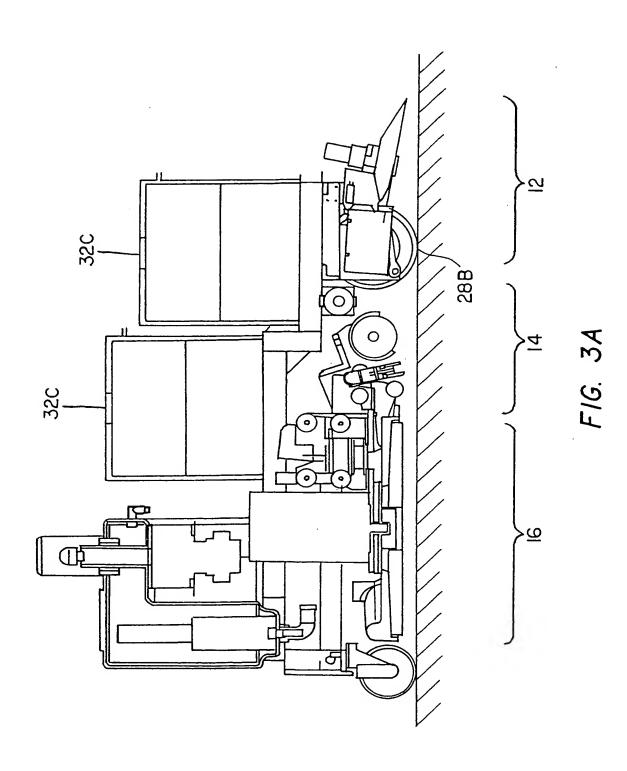














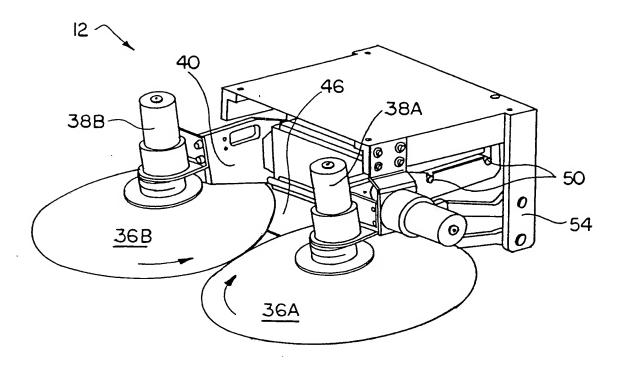


FIG. 4

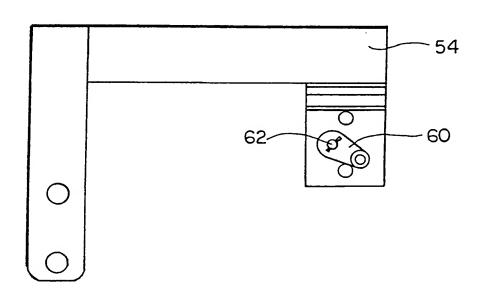
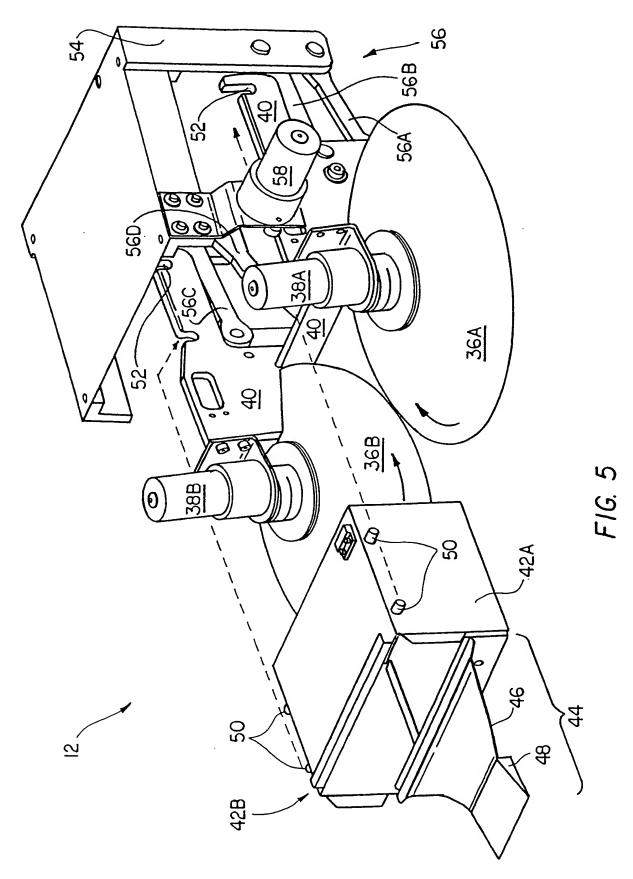
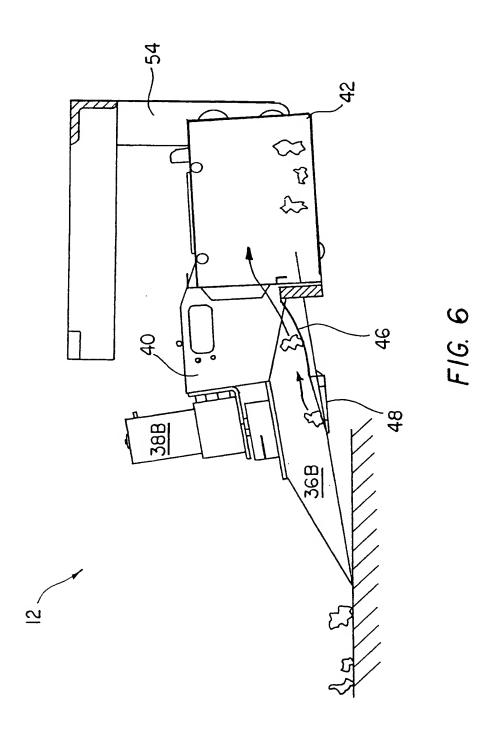


FIG. 4A











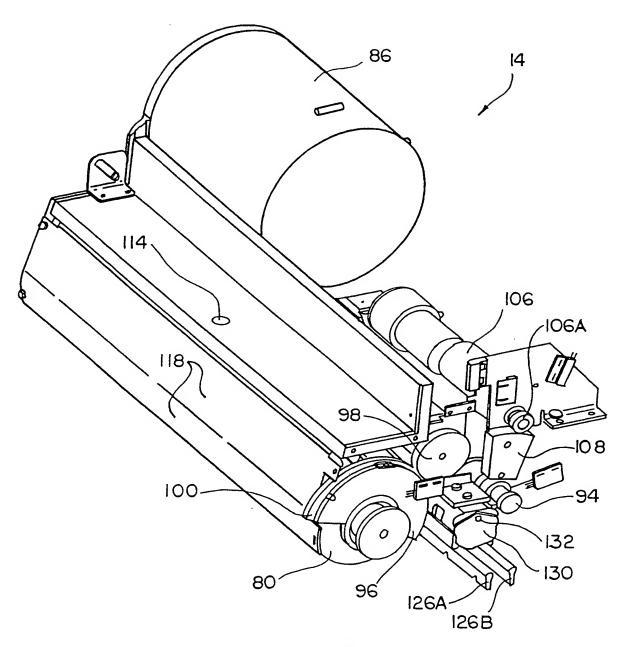
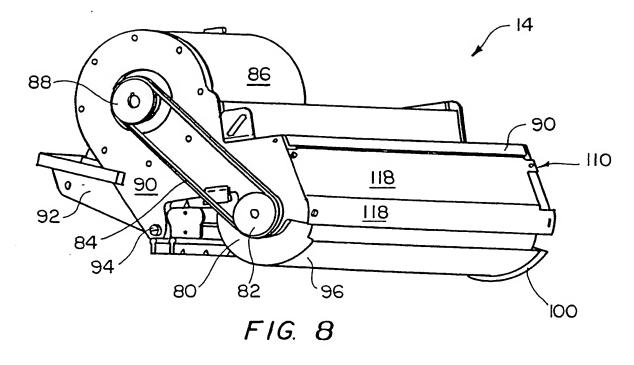
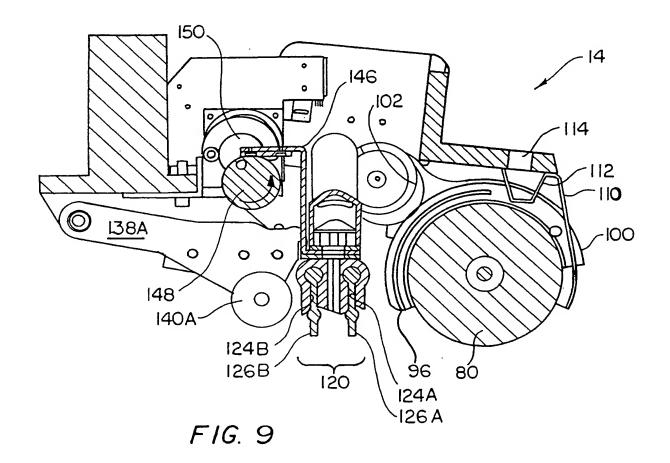
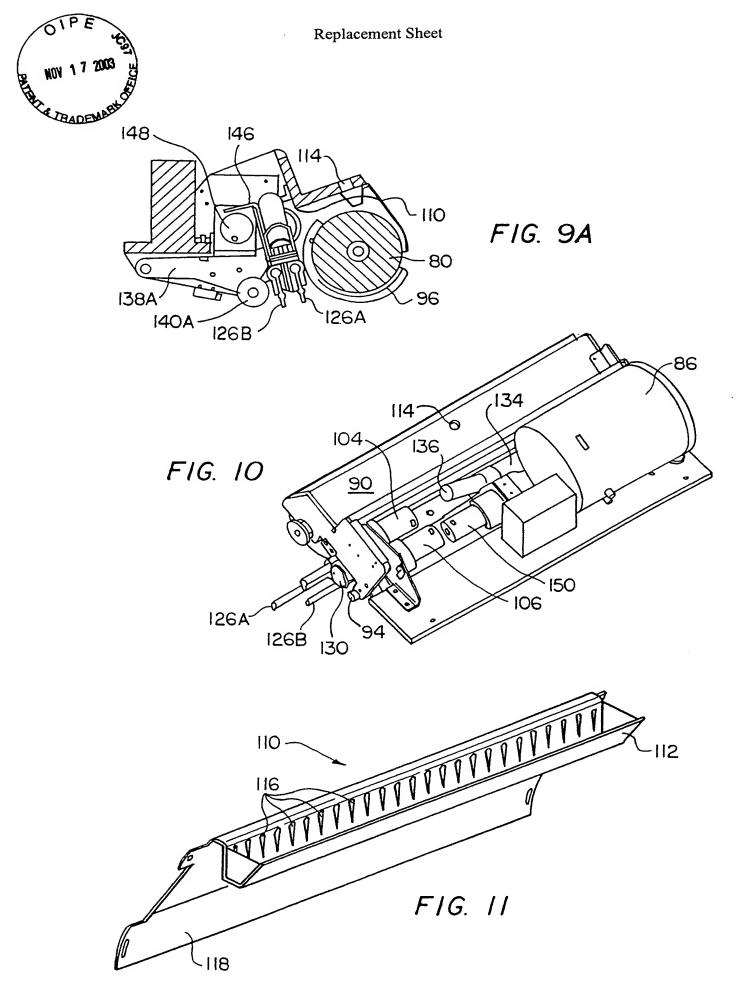


FIG. 7

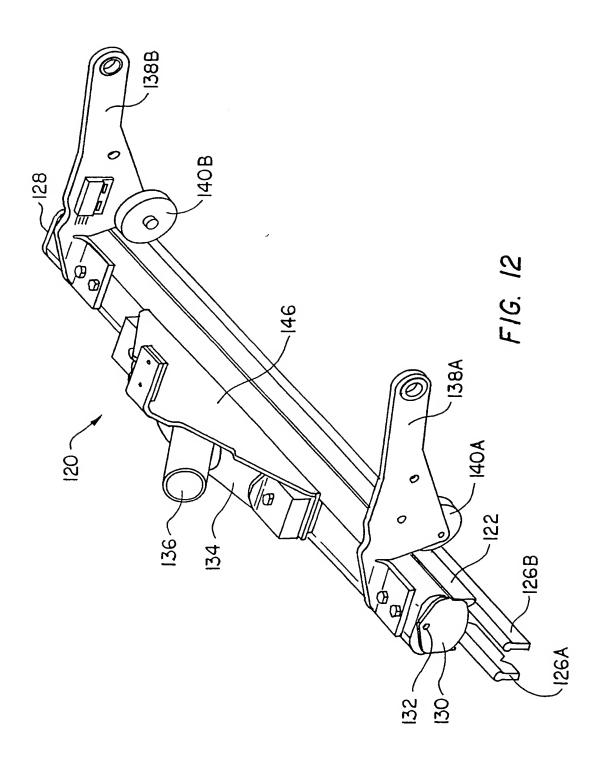




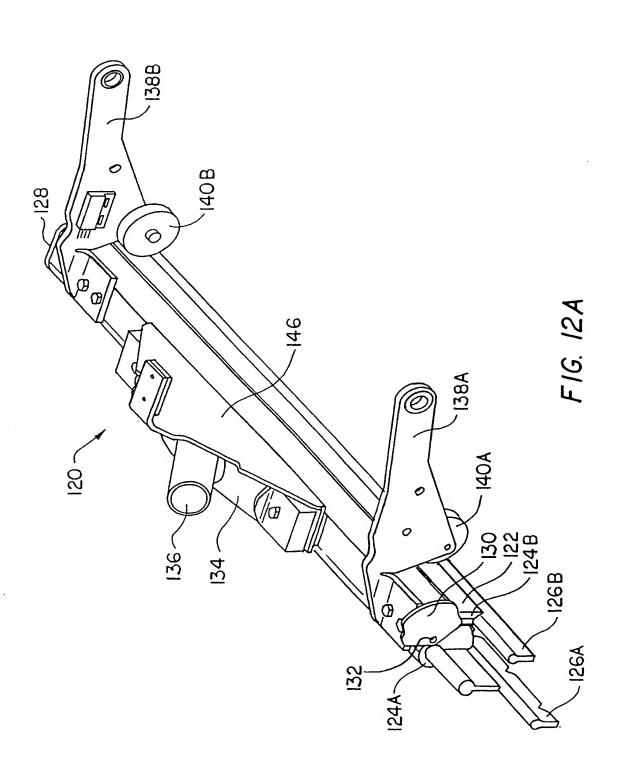




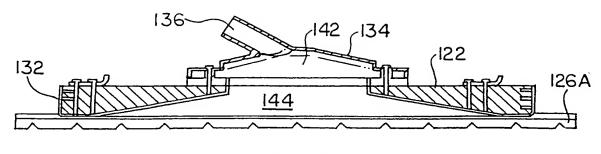












F1G. 13

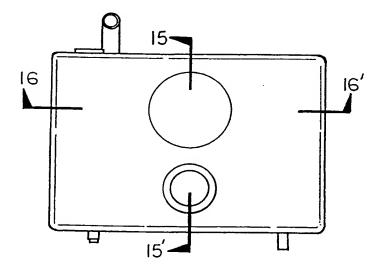
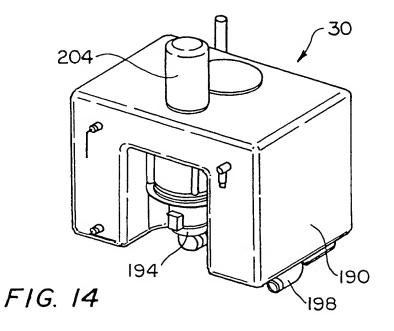
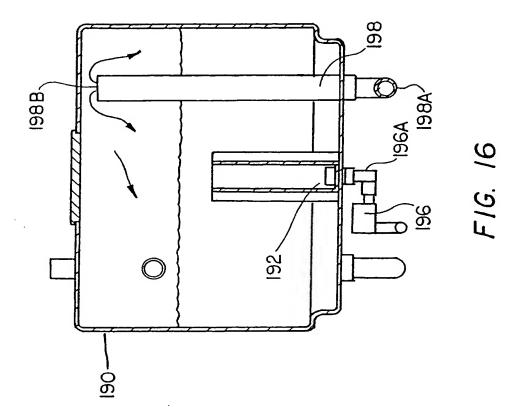
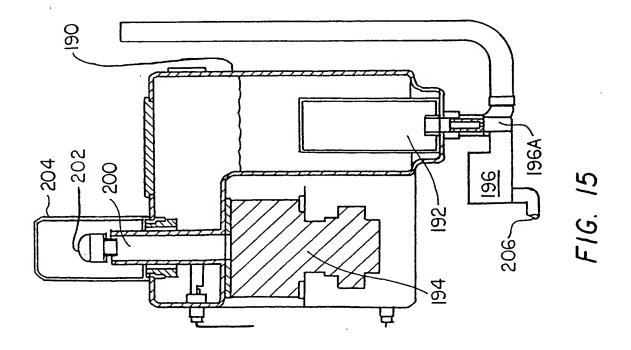


FIG. 14A

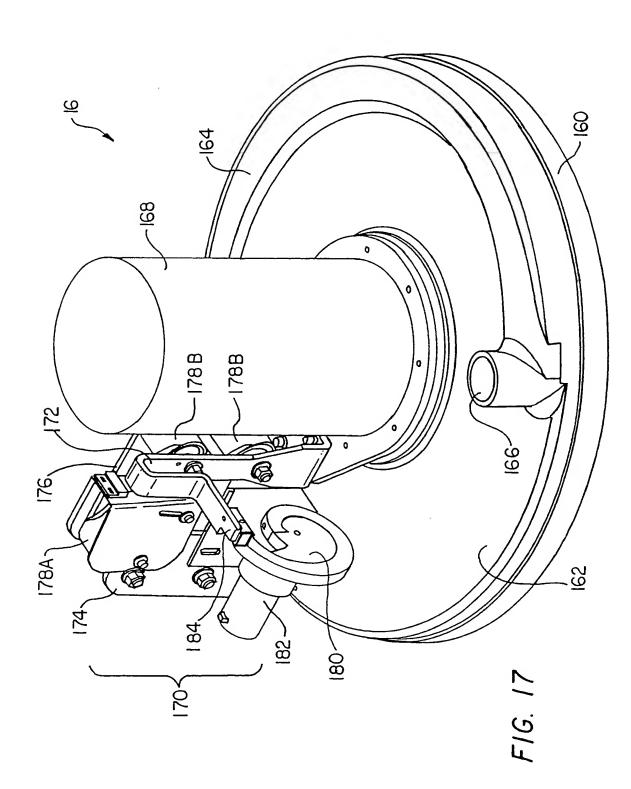














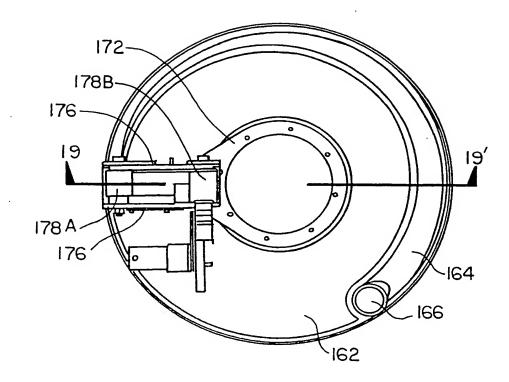
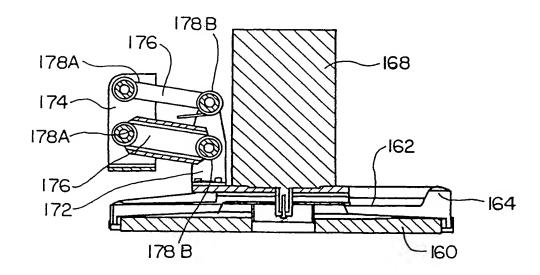
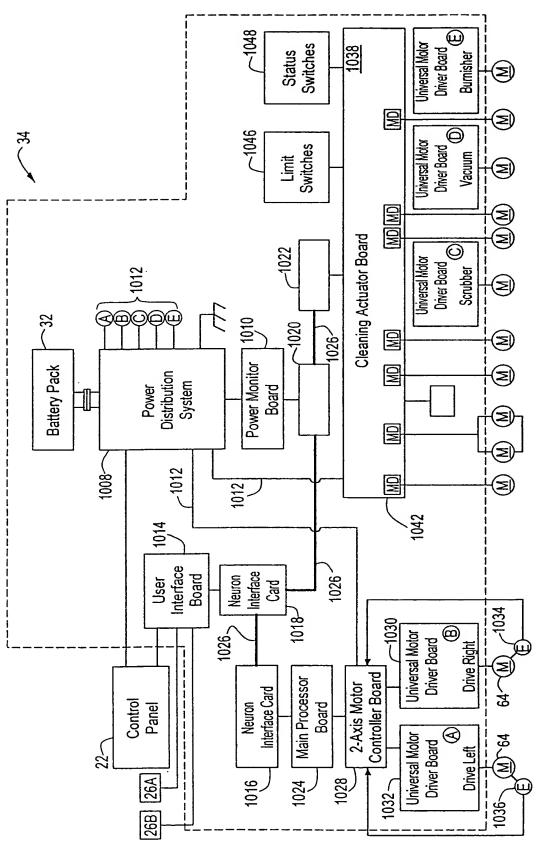


FIG. 18



F1G. 19





F/G. 20



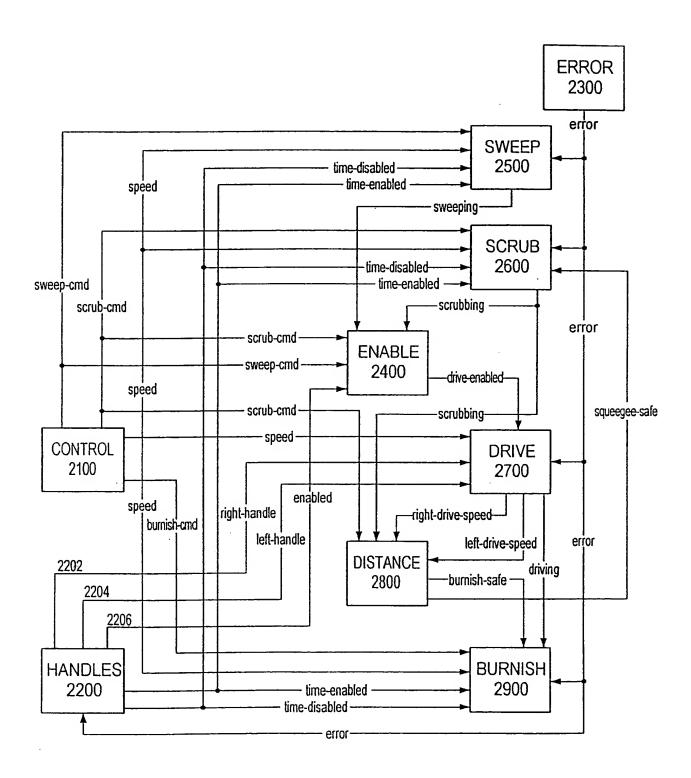


FIG. 21



FIG. 24	2200
HANDLES variables: enable-time, disable-time	2200
if (NOT error) {   right-handle is ui-right-handle   left-handle is ui-left-handle	} 2202 } 2204
if (right-handle or left-handle) {     disable-time is FALSE     time-disabled is FALSE     if (NOT enable-time)     enable-time = current time	2206
time-enabled = current time - enable-time } else {     enable-time is FALSE     time-enabled is FALSE     if (NOT disable-time)	) 2208
disable-time = current time time-disabled = current time - enable-time } enabled is (right-handle OR left-handle)	<b>}</b> 2210
else {     enabled is FALSE     right-handle is FALSE     left-handle is FALSE     time-enabled is FALSE     time-disabled is FALSE }	2212

# ERROR \*\*low level software filters the hopper full sensor\*\* if (ui-hopper-missing OR ui-tank-overflow OR ui-tank-empty OR system-error) } 2302 error is TRUE



DISTANCE

**2800** 

```
variable: burnish distance, squeegee distance
                                                               2802
if (scrub-cmd AND scrubbing) {
 if (NOT burnish-distance)
  burnish-distance = 0
  burnish-distance = burnish-distance +
                                                                2804
   DistanceFunction (right-drive-speed, left-drive-speed, rate)
else
 burnish-distance = FALSE
if (scrubbing)
                                                                2806
 squeegee-distance = FALSE
 squeegee-time = FALSE
else
                                                               2808
 if (NOT squeegee-distance)
  squeegee-distance = 0
  squeegee-time = current-time + squeegee-timeout
                                                               2810
  squeegee-distance = squeegee-distance +
                                                               2812
   DistanceFunction (right-drive-speed, left-drive-speed, rate)
                                                               2814
if (squeegee-time) {
 if ( (squeegee-distance > safe-distance-to-squeegee) OR
                                                               2816
   (current-time > squeegee-time))
  squeegee-safe is TRUE
                                                               2818
 else
  squeegee-safe is FALSE
if (burnish-distance > safe-distance-to-burnish)
 burnish-safe is TRUE
                                                               2822
else
                                      FIG. 29
```

### CONTROL

sweep-cmd is ui-sweep-cmd scrub-cmd is ui-scrub-cmd burnish-cmd is ui-burnish-cmd speed = ui-speed

FIG. 23

<sup>\*\*</sup> sweep, scrub, and burnish buttons polled at low level \*\*



\_\_2400

#### **ENABLE**

drive-enabled is (enabled AND (NOT(sweep-cmd XOR sweeping)) AND (NOT (scrub-cmd } 2402 XOR scrubbing)))

FIG. 25

```
DRIVE
** run at speed-ramp-rate times per second **
 if (right-wheel-target-speed is NOT right-wheel-current-speed)
  right-wheel-current-speed = right-wheel-current-speed + minimum of:
                                      speed-ramp-step
                                      (right-wheel-target-speed - right-
                                                                                2702
wheel-current-speed)
 if (left-wheel-target-speed is NOT left-wheel-current-speed)
  left-wheel-current-speed = left-wheel-current-speed + minimum of :
                                      speed-ramp-step
                                      (left-wheel-target-speed - left-
wheel-current-speed)
 right-drive-speed = right-wheel-current-speed
 left-drive-speed = left-wheel-current-speed
}
                                                                            2704
if (drive-enabled AND (NOT error) ) {
                                                                            2706
 if (left-handle)
  right-wheel-target-speed = ConvertSpeedFunction (speed)
                                                                            2708
  right-wheel-target-speed = speed=wheel-stop
 if (right-handle)
  left-wheel-target-speed = ConvertSpeedFunction (speed)
 else
  left-wheel-target-speed = speed-wheel-stop
 if (right-handle OR left-handle)
  if (NOT driving)
   driving is TRUE
 else
  if (driving)
   driving is FALSE
}
else (
 right-wheel-target-speed = speed-wheel-stop
                                                                            2718
 left-wheel-target-speed = speed-wheel-stop
 if (driving)
  driving is FALSE
}
                                      FIG 28
```



# **SWEEP**

```
if (sweep-cmd AND (speed is NOT reverse) AND (NOT error) ) (
                                                                    } 2502
 if (time-enabled > delay-on-sweep-start)
  if (sweeper is off)
    turn sweeper on
                                                                       2504
 if (time-enabled > delay-on-sweep-lower)
  if (sweeper is up)
    sweeper to down
  else
                                                                      2506
    if (NOT sweeping)
    sweeping is TRUE
 if (time-disabled > delay-off-sweep-raise)
  if (sweeper is down)
                                                                      2508
   raise sweeper
   if (sweeping)
    sweeping is FALSE
 if (time-disabled > delay-off-sweep-stop)
                                                                       2510
  if (sweeper is on)
   turn sweeper off
}
else {
 if (sweeper is down)
  sweeper to up
                                                                      2512
  if (sweeping)
    sweeping is FALSE
 if (sweeper is on)
 turn sweeper off
}
```

FIG. 26



```
if (scrub-cmd AND (speed is NOT reverse) AND (NOT error) ) (
                                                                         } 2602
 if (time-enabled > delay-on-scrub-start) (
  if (shroud is closed)
    open shroud
  if (scrubber is off)
    turn scrubber on
                                                                            2604
  if (vacuum is off)
   turn vacuum on
  if (squeegee is up)
    lower squeegee
  if (solenoid is closed)
    open solenoid
 if (time-enabled > delay-on-scrubber-lower) {
  if (pump is off)
   turn pump on
                                                                            2606
  if (scrubber is up)
    lower scrubber
  else
    if (NOT scrubbing)
    scrubbing is TRUE
 if (time-disabled > delay-off-scrubber-raise) (
  if (scrubber is down)
    raise scrubber
                                                                            2608
    if (scrubbing)
    scrubbing is FALSE
  if (pump is on)
    turn pump off
 if (time-disabled > delay-off-scrubber-stop) (
  if (scrubber is on)
   turn scrubber off
                                                                            2610
  if (solenoid is open)
    close solenoid
  if (squeegee-safe) (
    if (shroud is open)
    close shroud
    if (squeegee is down)
                                                                            2612
    raise squeegee
    if (vacuum is on)
    turn vacuum off
  }
```

FIG. 27



```
else(
 if (scrubber is down)
  raise scrubber
  if (scrubbing)
   scrubbing = FALSE
                                            2614
 if (pump is on)
  turn pump off
 if (scrubber is on)
  turn scrubber off
 if (solenoid is open)
  close solenoid
if ( (speed is reverse) OR error) (
 if (shroud is open)
  close shroud
                                            2616
 if (squeegee is down)
  raise squeegee
 if (vacuum is on)
  turn vacuum off
else if (squeegee-safe) (
 if (shroud is open)
  close shroud
                                            2618
 if (squeegee is down)
  raise squeegee
 if (vacuum is on)
  turn vacuum off
```

FIG. 27A



## **BURNISH**

```
if (burnish-cmd AND (speed is NOT reverse) AND (NOT error) ) (
                                                                         }2902
 if (time-enabled > delay-on-burnisher-start) (
  if (burnisher off)
                                                                           2904
    turn burnisher on
  if (burnish-safe AND driving) (
    if (burnisher NOT down)
    burnisher to down
                                                                           2906
    else
    if (NOT burnishing)
     burnishing is TRUE
  {
  else
                                                                           2908
    if (burnisher NOT at middle)
     burnisher to middle
 if ( (time-disabled > delay-off-burnish-stop) OR (NOT driving) ) (
  if (burnisher is down)
    burnisher to middle
                                                                           2910
    if (burnishing)
    burnishing is FALSE
  if (burnisher is on)
    turn burnisher off
 if (time-disabled > delay-off-burnish-raise)
                                                                           2912
  if (burnisher NOT up)
    burnisher to up
}
else{
 if (burnisher is down)
  burnisher to up
                                                                           2914
  if (burnishing)
    burnishing is FALSE
 if (burnisher is on)
  turn burnisher off
}
```